

Paper Mechatronics: Creating High-Low Tech Design Kits to Promote Engineering Education

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Cyberlearning #1451463



Paper Mechatronics
R & D TEAM:

Lawrence Hall of Science at UC Berkeley
Univ. of Colorado at Boulder - Craft Technology Lab

Challenges

- Learning is teacher-driven rather than interest-driven and learner-centered
- Current learning materials have limited adaptability, expressivity, and accessibility
- Robotics kits are too expensive for most families
- The culture of robotics favors competition vs. other ways to participate in engineering



How do we broaden participation so all kids can learn engineering (robotics & mechatronics)?

Paper Mechatronics

Mechatronics

- Design of Microprocessor-based Mechanical Systems
- Real-time computing
- Electromechanical components
- Feedback, control fundamentals
- Architecture of microprocessors
- Concepts of time in computing engr
- Programming



Craft Making

- Inviting
- Interest-driven
- Learner-centered
- Hands-on
- Joyful
- Expressive
- Materials-rich

Why paper?

- Ubiquitous in most homes, schools, cafeterias
- Papercrafts are joyful and familiar (origami, airplanes, paper dolls, ...)
- Easy adaptable, cut, shaped, formed
- Layering with expressive materials like paint, glitter
- Recycable, compostable

Draft Design Framework

INPUT

Paper PCBs:

- switch
- knob
- encoder
- photoresistor
- distance sensor
- microphone

CONTROL

Software /
Ardubloks

OUTPUT

Paper PCBs:

- motor
- servo
- LED
- display (LED matrix)
- speaker

MECHANISMS

- ✓ cam & follower
- ✓ linkages
- gears
- ~~sprockets and chains~~
- ~~pulleys and belts~~
- pneumatics?
- ~~hydraulics~~

Avoid: Breadboarding

Syntax

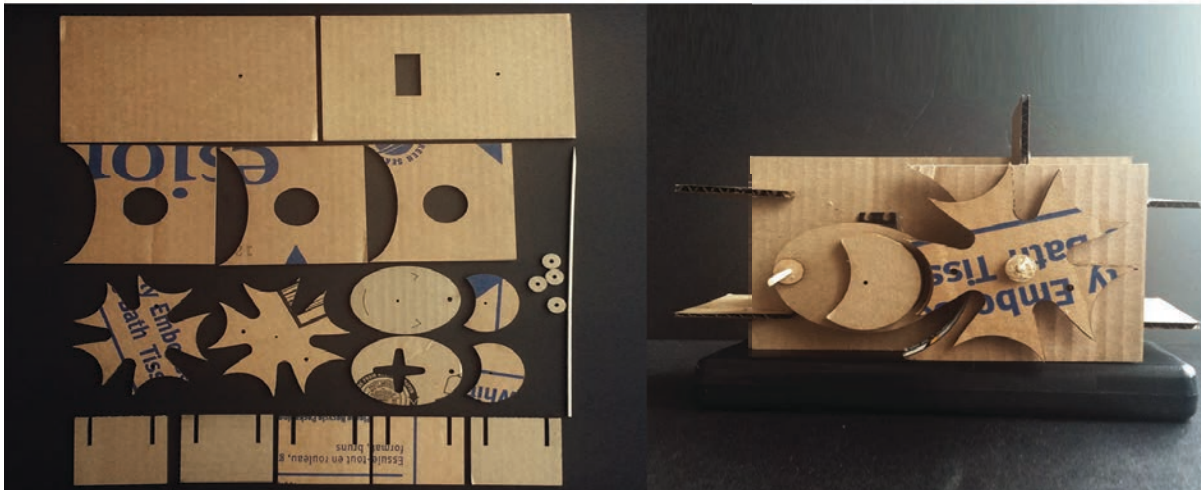
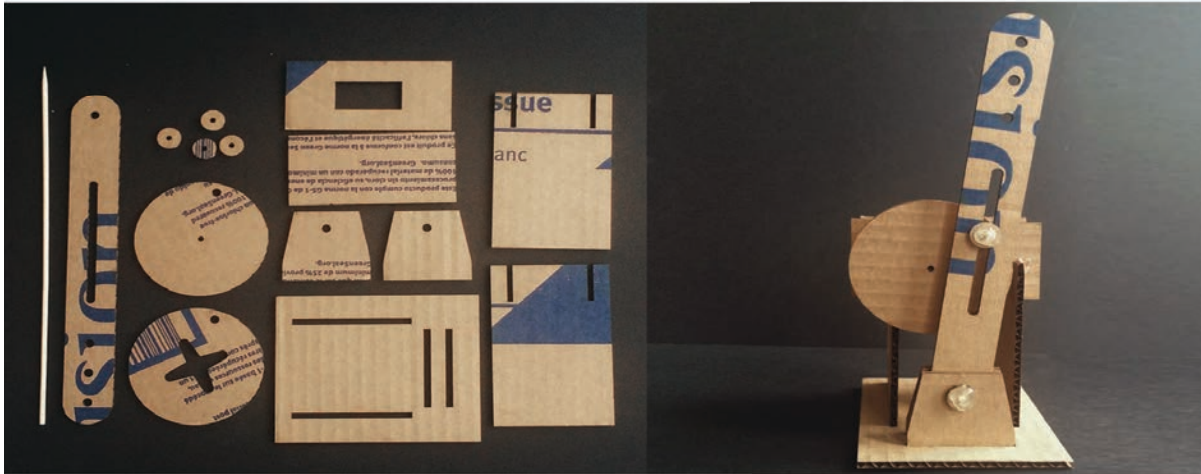
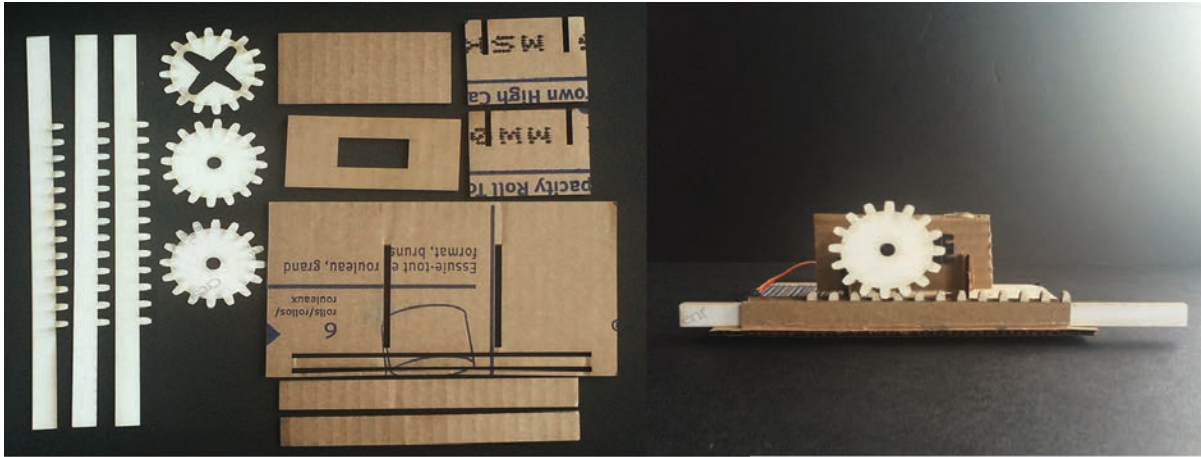
Tight Tolerances

Aim for:

Low-Cost

**Common Tools or
Digifab Tools**

**Paper-based
materials**



Laser-cut
components

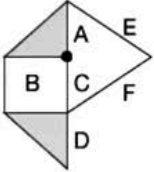
Classical
Mechanisms

Computer-
controlled


Work of Graduate Students:

- HyunJoo Oh
- Abhishek Narula
- Jiffer Harriman

Change Design




A: 5 B: 5
 C: 4 D: 5
 E: 6 F: 6




X: 0 Y: 5
 R: 1

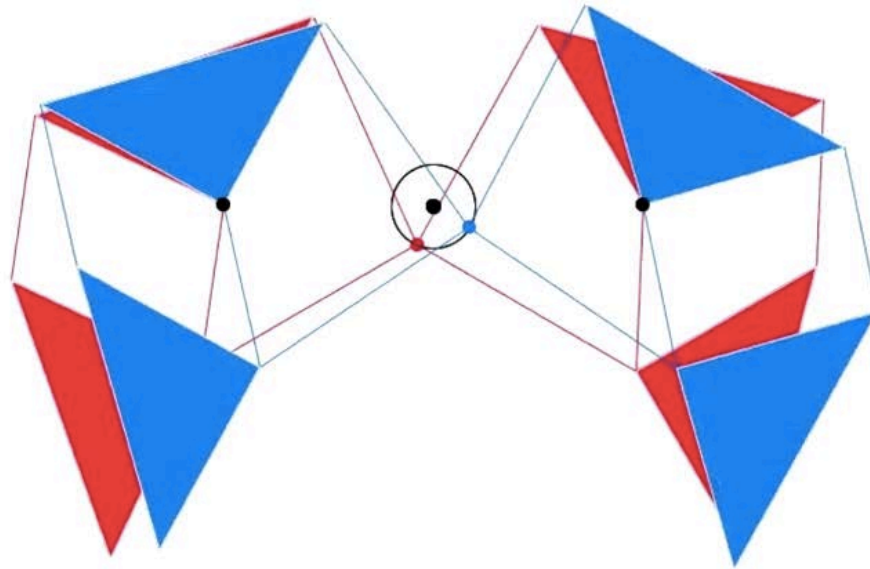
Select Color



Add New ☐
 Clear All ☐
 Reset ☐

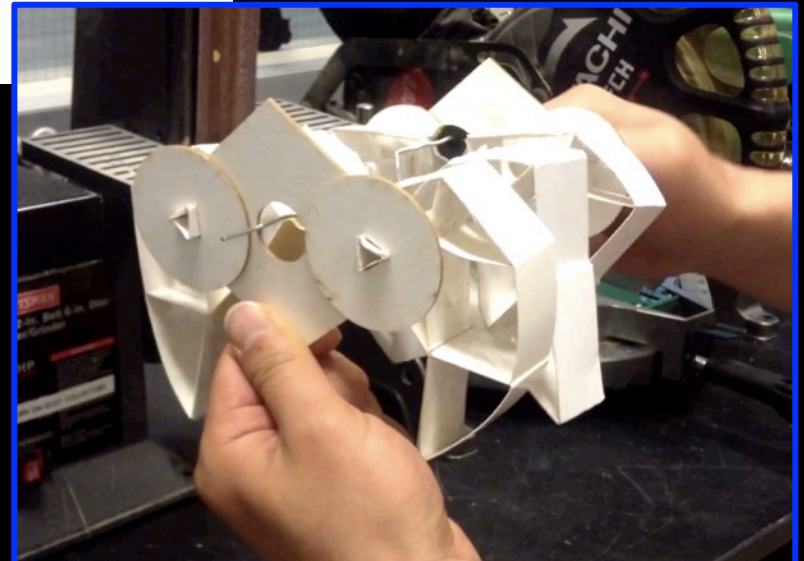
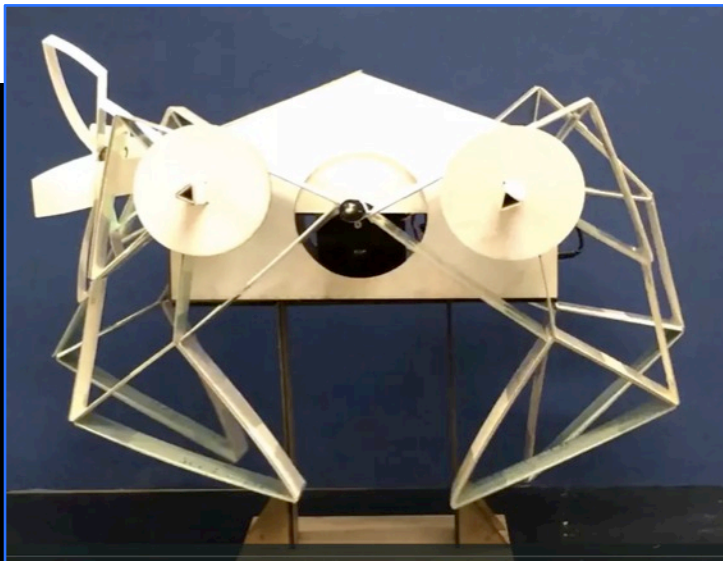
View the Map 

Fall 2014

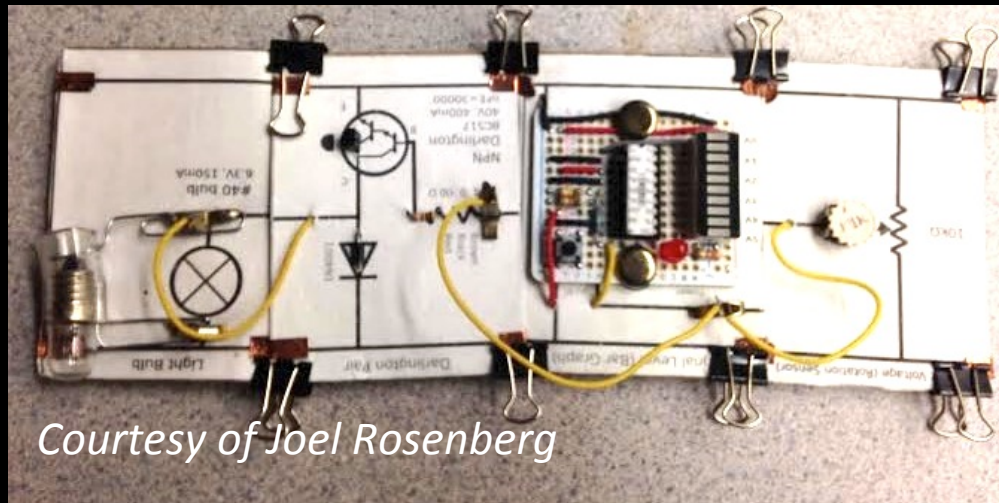


Motion modeling
software for
paper components

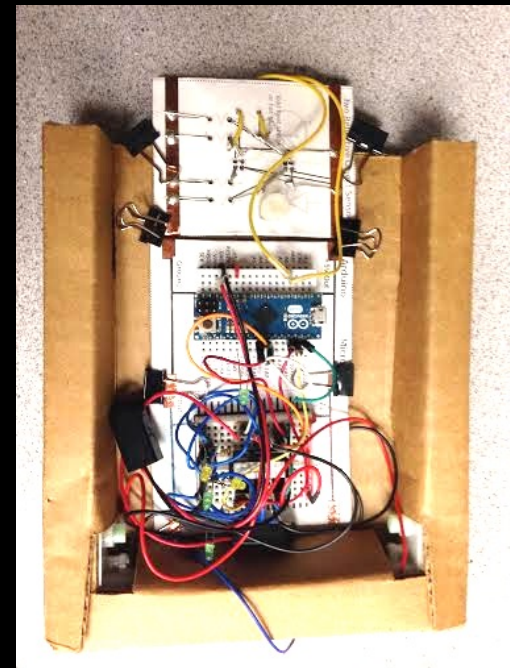
*Hyun Joo Oh,
Mike Eisenberg,
Mark Gross,
CU Boulder*



Cardboard sub-components

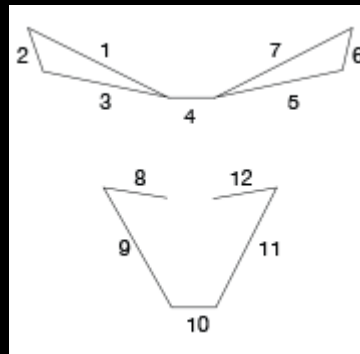
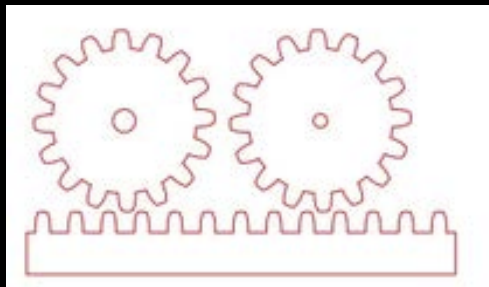


Courtesy of Joel Rosenberg



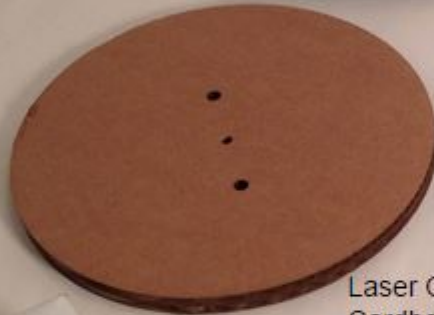
Tracing Bot

Digital design templates



Kits and Boards

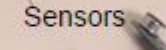
**Our
parts:**



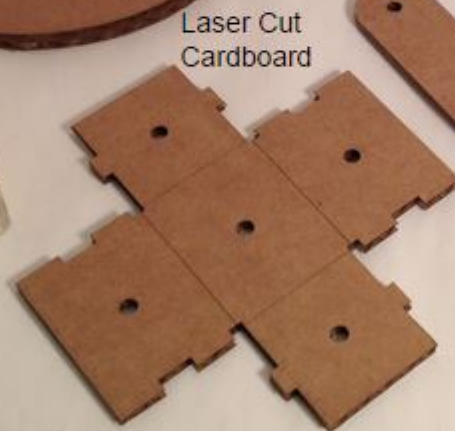
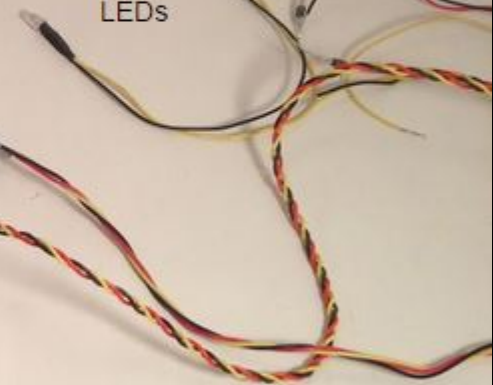
MakeDos
(old version)



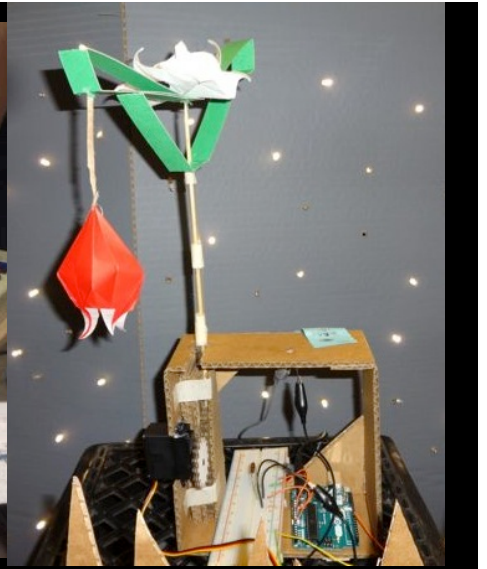
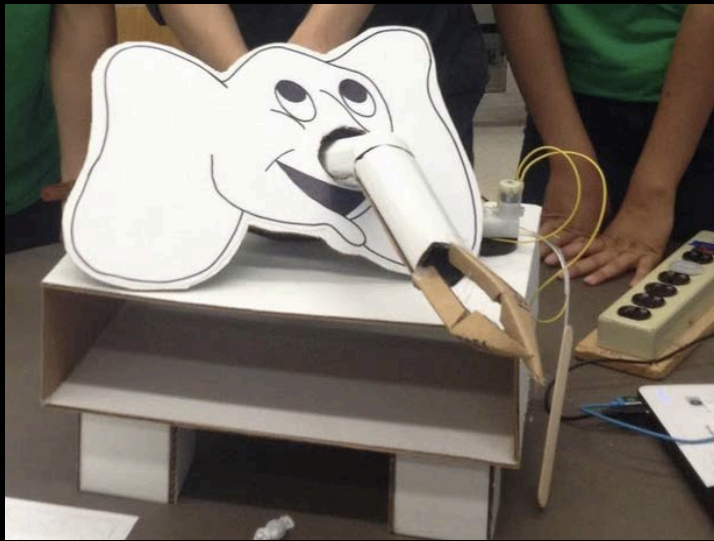
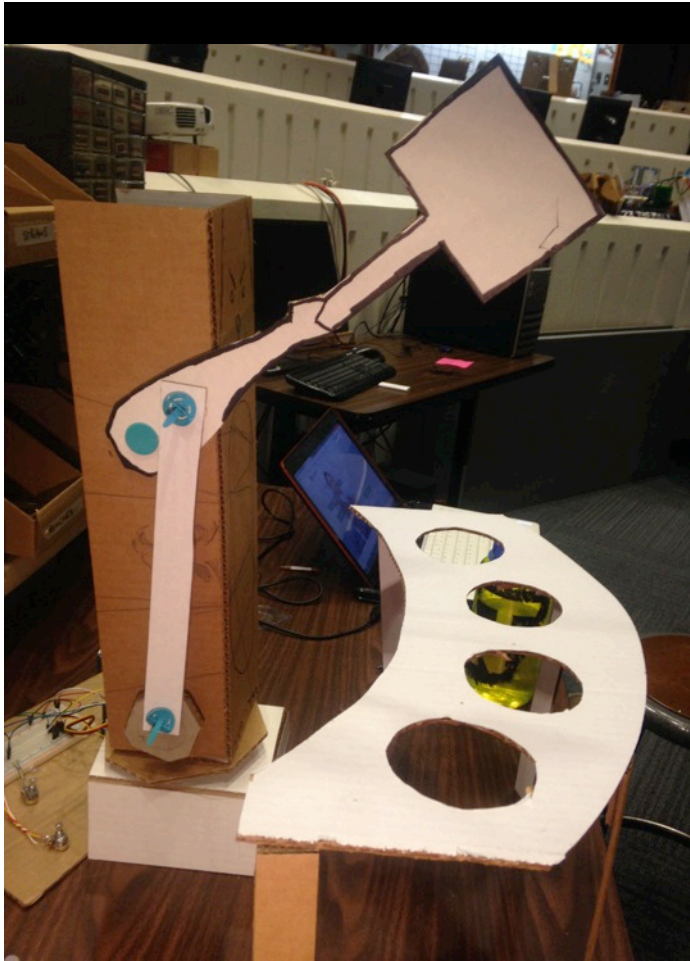
Sensors



LEDs



+Computer,
Extra Cardboard and
craft supplies



THE LAWRENCE
HALL OF SCIENCE



TechHive

Design Studies

- Paper Flower Garden (“Tiki Room”)
- Cereal Box Hackathon
- Robot Theaters
- Hackathon - Robot Petting Zoo
- High school physics – RPZ
- Percussive Instruments Workshop





Children's Creativity Museum
Robot Petting Zoo

Activation Dimension	Pre	Post	Mean Difference	paired t-test result
fascination	3.41	3.73	0.32	0.002
values	3.08	3.31	0.23	0.001
competency belief	3.05	3.33	0.28	0.004
innovation stance	3.06	3.47	0.41	0.000

*Participants demonstrate a statistically significant increase in their levels of **fascination, value, competency belief, and innovation stance** from pre-survey to post-survey.*

Robot Petting Zoo



[Lighthouse Charter School Oakland](#)



We envision an **expressive**, technology-enhanced medium be designed to enable **all learners** to learn **mechatronics** while creating what they imagine using the affordances of **paper**.

From Papercrafts to Paper Mechatronics

Sherry Hsi, UC Berkeley

Mike Eisenberg, CU Boulder

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