

BiD, Wicked Problems & Design Thinking

 UC Berkeley Interdisciplinary Design Seminar, Spring 1989





Wicked Problems: Define by two UC Berkeley Professors

- Rittel, Horst W. J.; Melvin M. Webber (1973).
 "Dilemmas in a General Theory of Planning" (PDF). Policy Sciences 4: 155–169.
- Churchman, C. West (December 1967). "Wicked Problems". Management Science 14 (4), 1967. doi:10.1287/mnsc.14.4.B141. (learned the expression from a Horst Rittel lecture at Berkeley)
- Death and life Jayne Jacobs, wicked problems 1961

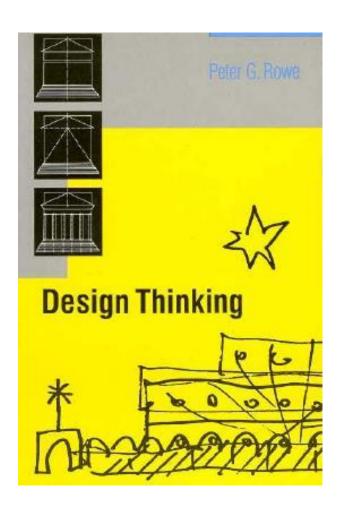


Wicked Problem Framing the Foundation for Design Thinking

- May not be solvable. Solutions may be better or worse.
- Can only be understood within socially complex contexts.
- Solutions require social learning processes.
- Requires iteration.
- Design methods & tools require developing a shared understanding of the problem.



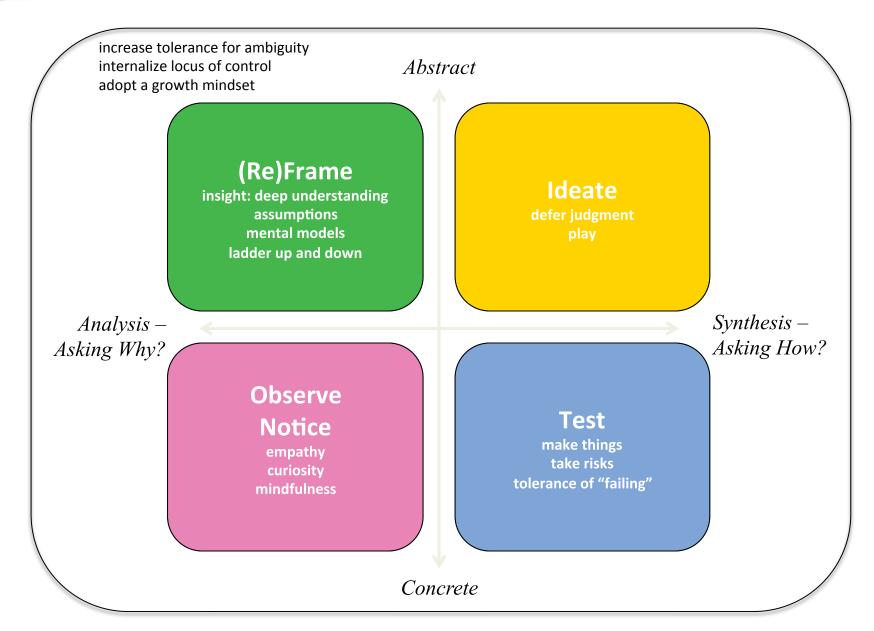
Rittel's Inspiration to Design Thinking



- Peter Rowe, 1987: Underlying structure of inquiry common to all designing. Limitations of a procedural view.
- Peter Rowe summarizes well-defined, ill-defined, and wicked problems from Horst Rittel.
- Design Thinking symposium, Delft University of Technology, 1991.
- Buchanan, Richard, "Wicked Problems in Design Thinking," *Design Issues*, vol. 8, no. 2, Spring 1992.
- Brown, Tim, Change by Design: How Design Thinking Transforms Organizations and Inspires Innovation, 2009.

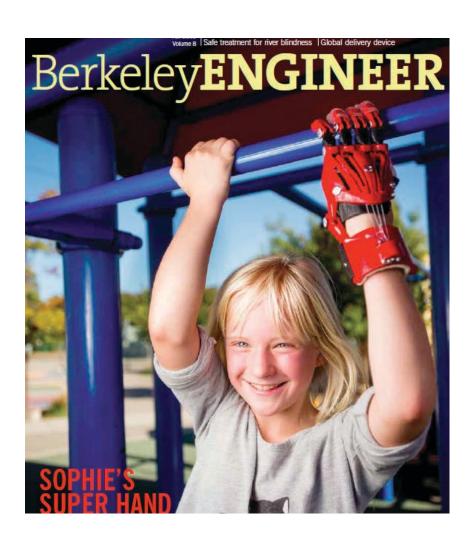


Berkeley's Model of Design Thinking & Skills Development





Sophi's Hand



- Berkeley Prosthetics Project
- Daniel Lim, Chris Meyers& Alexa Koening





Design Roadmapping: User Experience Focused Strategy

✓ **Tangible Design Roadmapping <u>Puzzles</u>**A set of puzzles for team based activities for managers, designers, and engineers. <u>Euiyoung Kim</u>

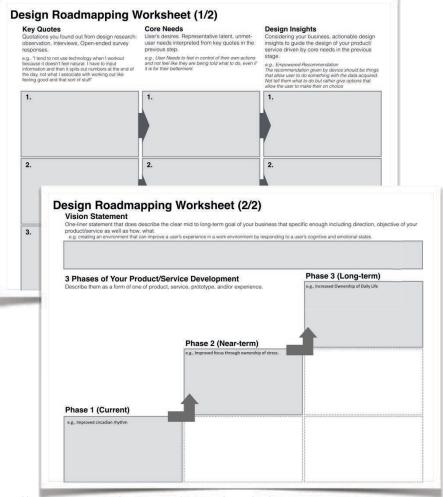






✓ Tangible Design Roadmapping Worksheets

A set of worksheets for individual design roadmapping exercises.

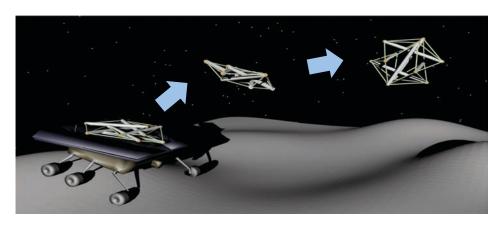


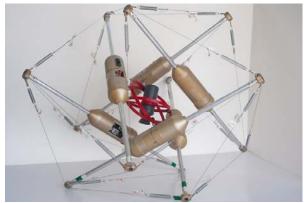
http://best.berkeley.edu/wp-content/uploads/2015/07/DESIGN-ROADMAPPING_Camera-Ready Final with-Abstract Letter.pdf



Tensegrity Robots: Space Exploration → Co-Robots

- 10 kg probe deliver 1 kg payload 1 km away
- Only lasts for hour or two (must be quick)
- Deliver payload accurately
- Handles difficult terrain (e.g., 30% slopes)
- Lower costs in mission to the Moon, Titan

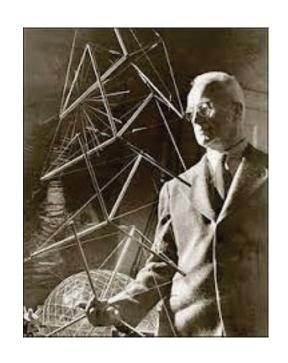






Tensegrity

- Coined by Buck Minster Fuller
- Art explored by Kennith Snelson in 1960's





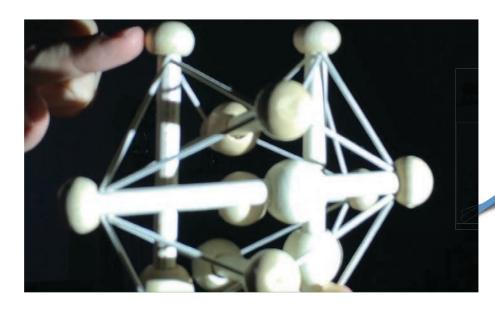


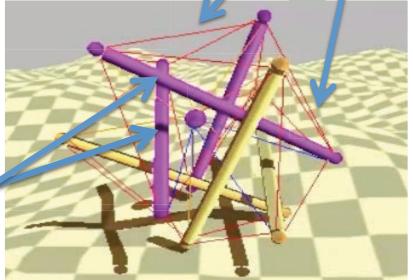


Robot Built from Tensegrity Structures

- What is a tensegrity structure?
 - Structure build from rods and cables
 - Rods do not touch each other

Cables



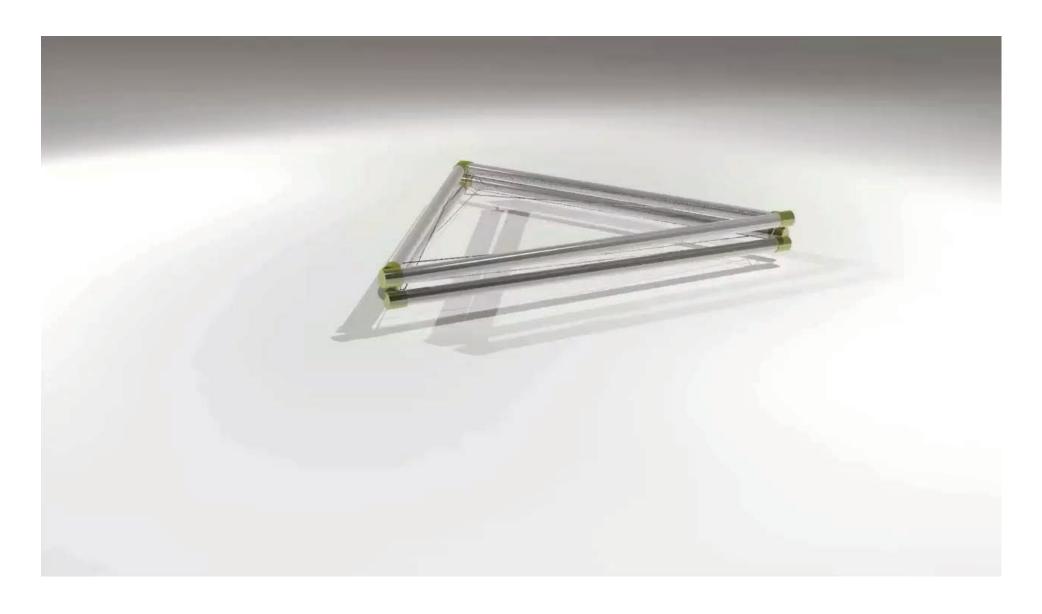








Multi-Function: Unpacking, Landing, & Mobility





Hopping and Rolling Tensegrity Robots

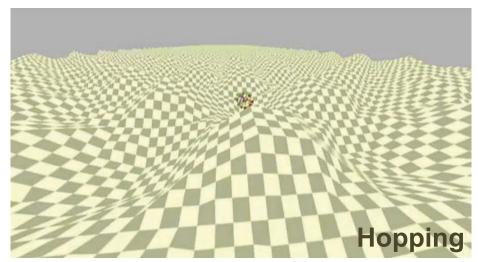
Lee-Huang Chen Kyunam Kim

Demo: 3:20-5:00 Jacobs Hall





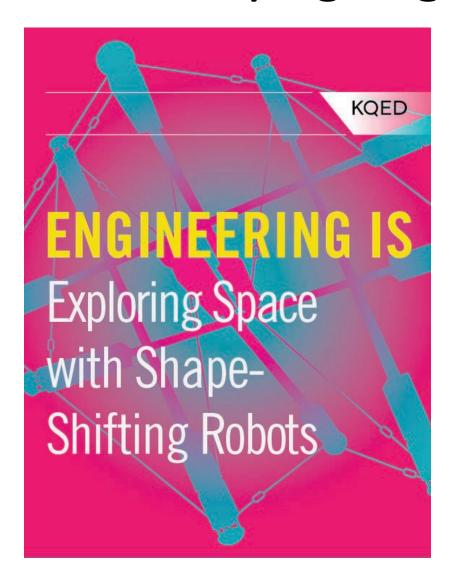






Diversifying Engineering

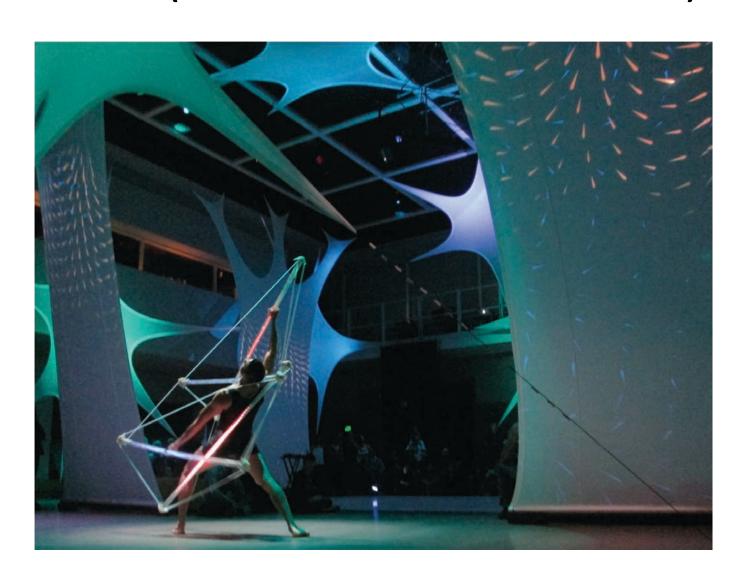






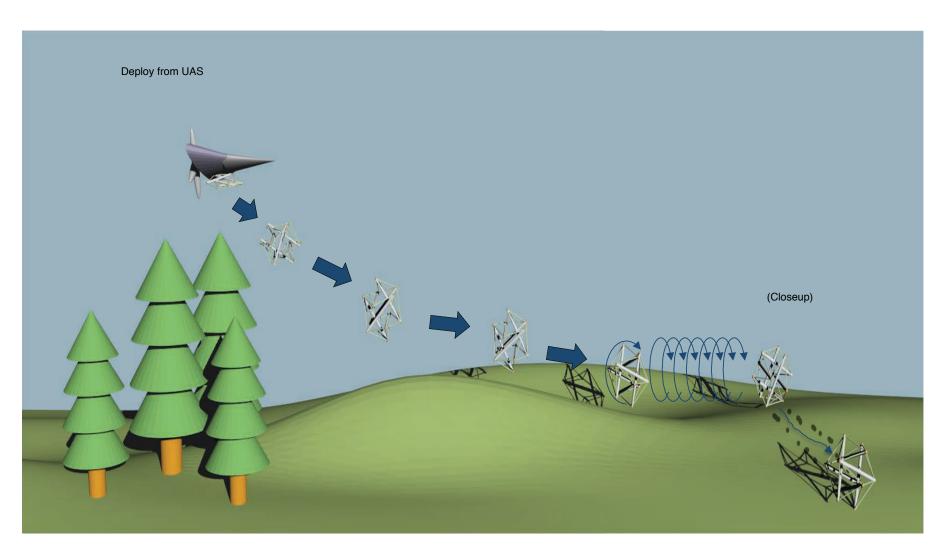


Synaptic Motion: Tensegrity-Inspired Dance (Colin Ho & Jodi Lomask)



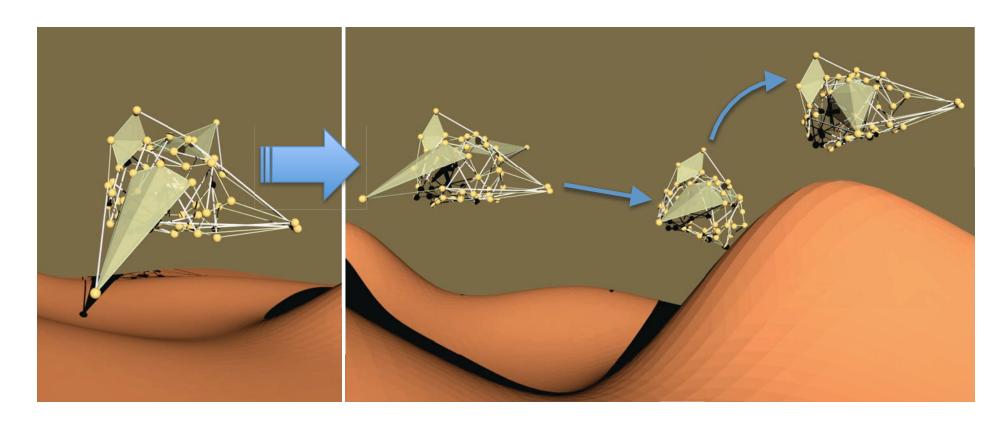


Future: UAV dropped Analog Demonstration



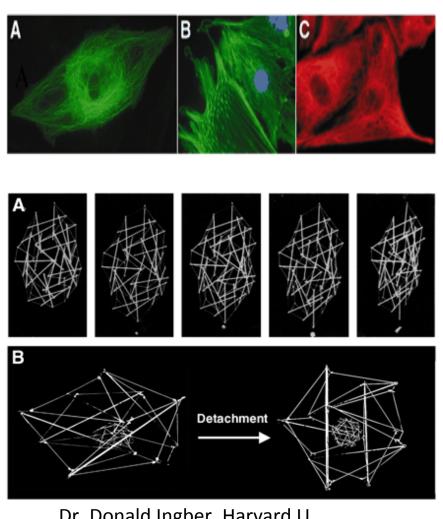


Future: SUPERBall Bird – Crash Proof Flight





Future: Tensegrity, Biology & Co-Robots



Dr. Donald Ingber, Harvard U.



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